



VAMP

Feeder protection relay type VAMP 140

formerly known as VPJ 140

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VAMP 140

- is fully numerical over current and earth fault relay
- has built-in disturbance recorder
- supports various communication protocols
- optionally accommodate an arc protection module
- can be an integrated part of the station level arc protection system



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Protection functionality

Three phase overcurrent

$I >, I >>, I >>>$

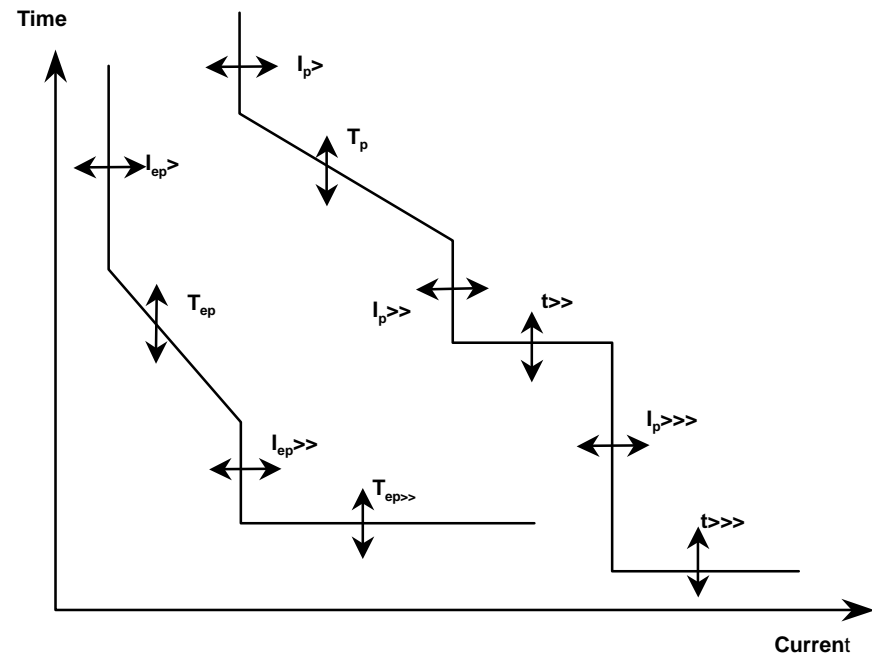
Earth fault overcurrent

$I_{ep} >, I_{ep} >>, I_{ep} >>>$

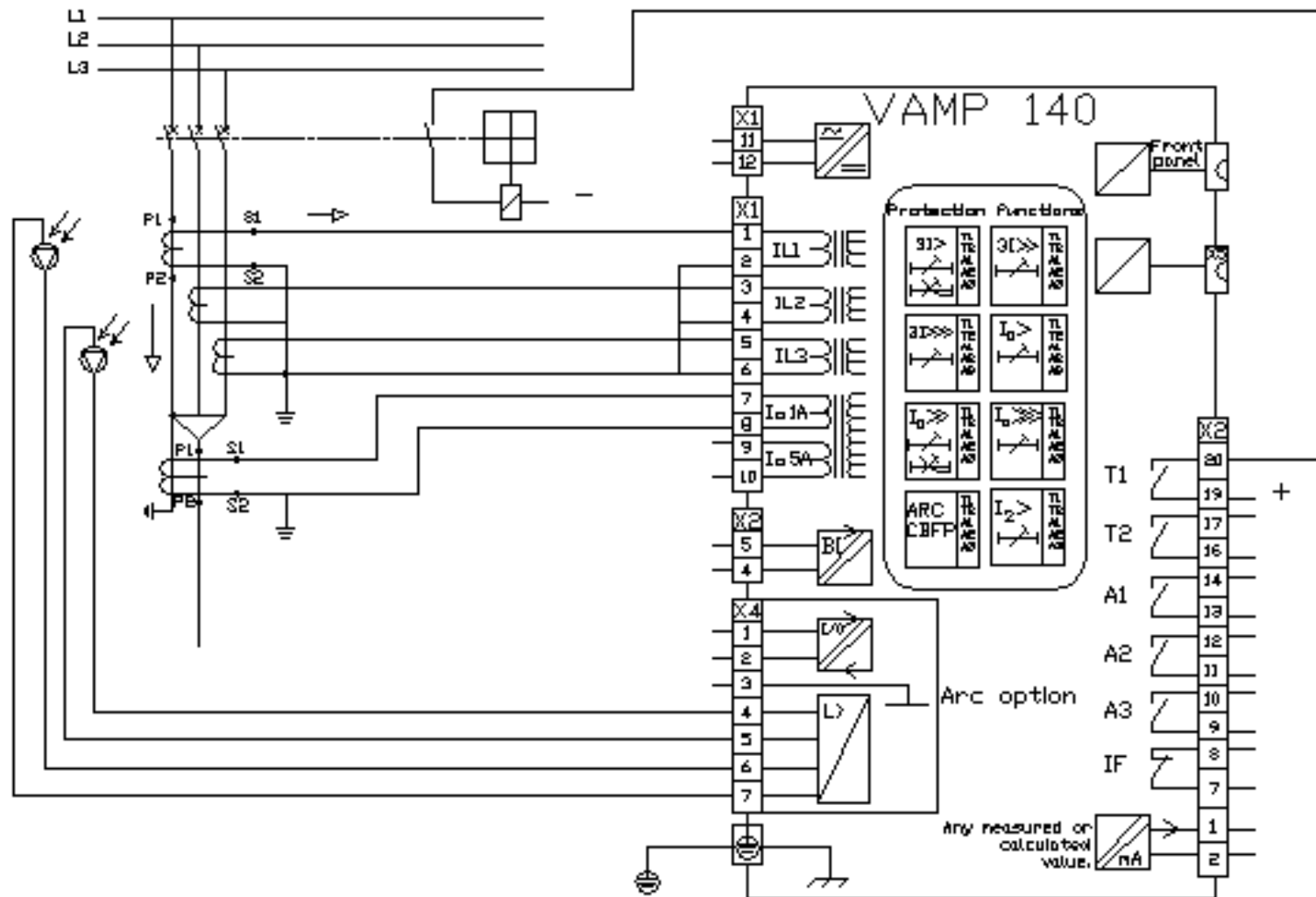
Current unbalance

Thermal overload

Arc protection (option)



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Additional functions

Disturbance recorder

Four analog and eight digital channels

Primary measurements

Phase currents I_{L1} , I_{L2} , I_{L3} , I_L , maximum of I_L

Residual current: I_o

Phase unbalance: I_2 / I_1

Frequency: f

Analog output

0 (4) ...20 mA

One measured signal (I_{L1} , I_{L2} , I_{L3} , I_L , I_o , I_2/I_1 , f and I_Fault) can be linked in the output

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Over current protection stages

Low set stage, 50 / 51

$I >$	$0,10 \dots 4,0 \times I_n$
$t >$	$0,08 \dots 300 \text{ s}$
Inverse curves	Normal, very, extreme and long time
k	$0,05 \dots 3.2$

High set stage, 50 / 51

$I >>$	$0,10 \dots 40 \times I_n$
$t >>$	$0,05 \dots 300 \text{ s}$

Super high set stage, 50 / 51

$I >>>$	$0,10 \dots 40 \times I_n$
$t >>>$	$0,05 \dots 300 \text{ s}$

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Earth fault protection stages

Sensitive earth fault stage, 50N / 51N

$I_{0(s)} >$ 0,005 ... 2,0 x I_n

$t_{0(s)} >$ 0,08 ... 300 s

Low set earth fault stage, 50N / 51N

$I_{0 >>}$ 0,02 ... 2,0 x I_n

$t_{0 >>}$ 0,05 ... 300 s

Inverse curves Normal, very, extreme and long time

k 0,05 ... 3.2

High set earth fault stage, 50N / 51N

$I_{0 >>>}$ 0,02 ... 4,0 x I_n

$t_{0 >>>}$ 0,05 ... 300 s

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Current unbalance

Current unbalance stage, 46

I_2 / I_1	5 ... 70 %
$t >$	1 ... 600 s

Thermal overload

Thermal overload stage, 49

$T >$	0,5 ... 1,2 x I_n
τ	2 ... 60 min
$T > \text{alarm}$	60 ... 99 %

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Arc protection

Arc protection $I >$, 50AR

$I >$

0,5 ... 10 x I_n

$t >$ (fixed)

14 ms

Arc sensor channels⁽¹⁾

L1, L2, L1/L2, L1/BI, L2/BI,
LI/L2/BI, BI

Arc protection $I_o >$, 50NAR

$I_o >$

0,05 ... 1,0 x I_n

$t_o >$ (fixed)

14 ms

Arc sensor channels⁽¹⁾

L1, L2, L1/L2, L1/BI, L2/BI,
LI/L2/BI, BI

1) The relay has two arc sensor channels (L1 and L2) as well as one binary channel (BI) for external light information

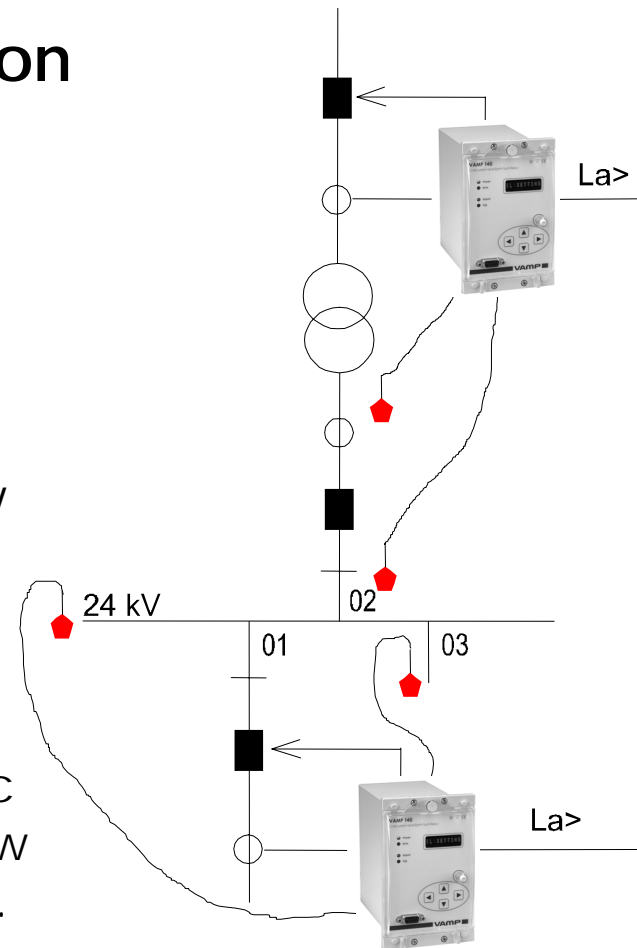
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Example of adaptive arc protection made by feeder protection relay

Adaptive means that the arc protection is selective regardless the direction of the power flow.

The light information is shared between protection relays but the trip is carried out by a relay which has both current and light signals activated.

This is a true case where the feed can be from several directions. In a conventional arc protection system the problem would be how to measure the current from the right feeder. Now the over current is detected automatically from the correct feeder.



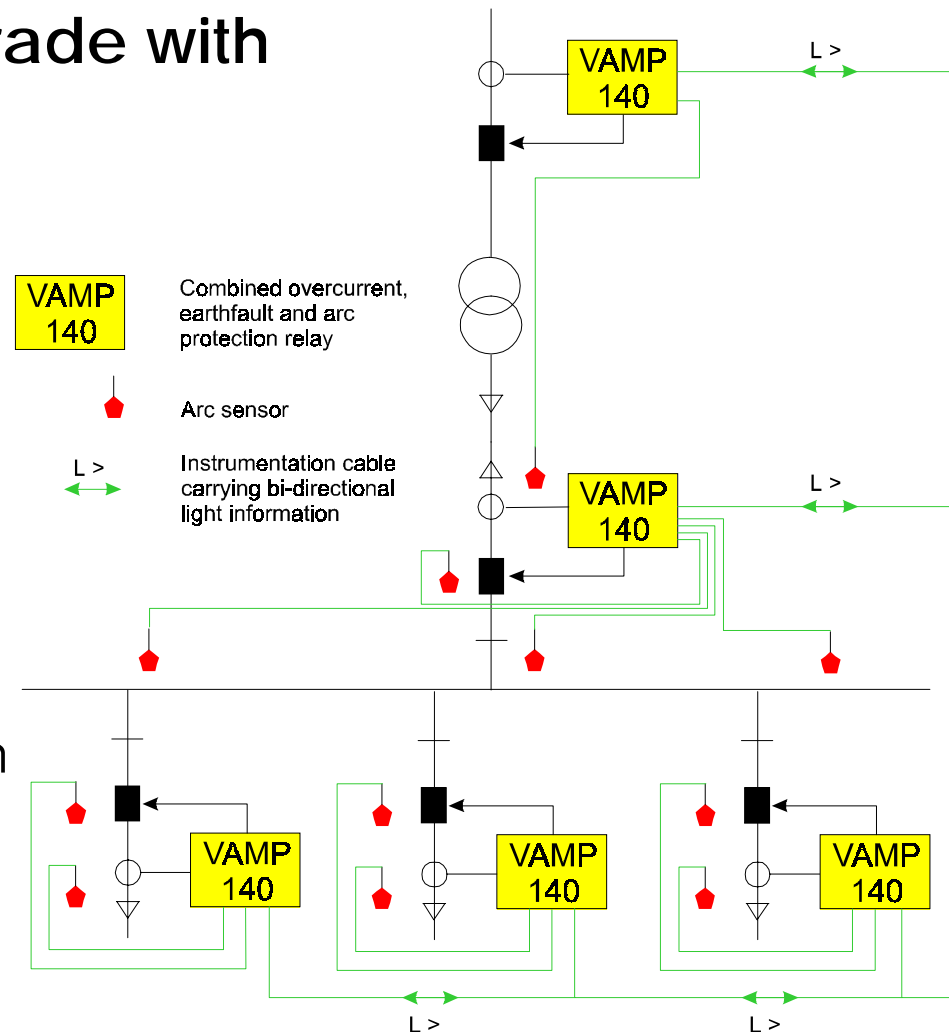
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Example of a relay up-grade with built-in arc protection

Numerical feeder protection relays provide conventional overload, short circuit and earth fault protection

Arc protection operates quickly in arc faults in every network connection mode

Light information is shared between every relay



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Disturbance recorder

Analog channels ⁽¹⁾	IL1, IL2, IL3, Io, f, I2/I1, I2/In, IL1rms, IL2rms, IL3rms, Irms, IL
Digital input (DI) channels ⁽¹⁾	Binary input Arc sensor channels L1 and L2, arc binary channel BI/O
Digital output (DO) channels ⁽¹⁾	Status of output relays and arc binary channel BI/O
Log mode	Saturated, overflow

1) Maximum twelve channels can be in simultaneous use

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Disturbance recorder

Pre trigger rate 0 ... 100%

Sample rate 16, 8 samples per cycle, every 10ms,
20ms, 200ms, 1, 5, 10, 15, 30s and 1 min

Recording time when IL1, IL2, IL3, Io, DI, DO channels are used

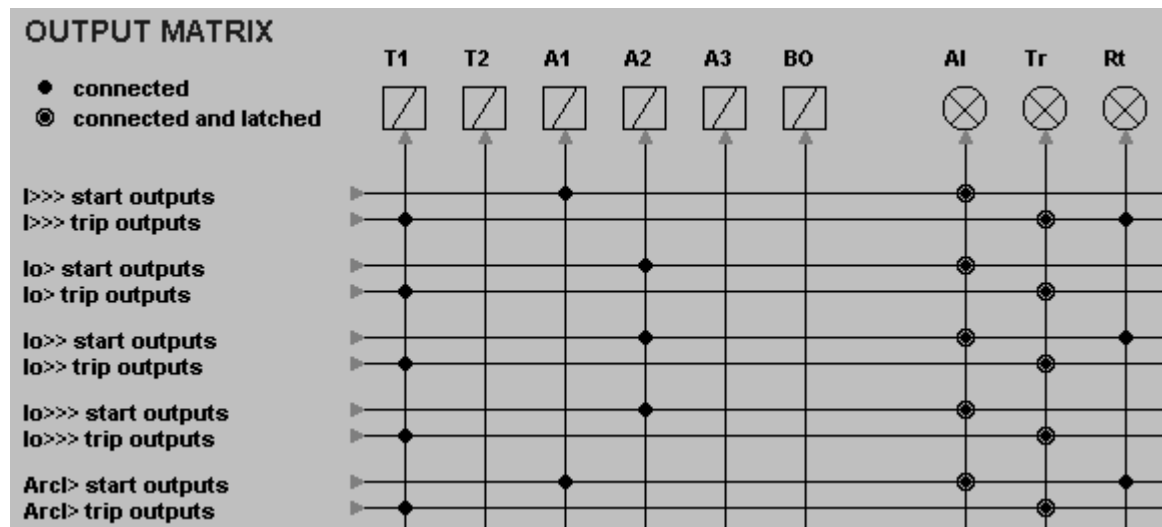
Sampling rate	Recording time in total
16 /cycle	3,75 s
8 / cycle	7,5 s
10 ms	20 s
20 ms	40 s
200 ms	400 s
1 s	2000 s
30 s	16,7 h
60 s	33,3 h

Number of separate records
can vary between 1 to 5
depending on the adjusted
recording length and total
recording time

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Disturbance recorder

The disturbance recorder views are used to set recorder and triggering conditions (Rt) in the VEPSET software.



DISTURBANCE RECORDER

RECORDER LINKS	
	IL1,IL2,IL3,Io,DI,DO
Add recorder link	-
Clear all links	-

Log mode	Saturated
Sample rate	16/cycle
Time	3.75 s
Pre trigger rate	50 %
Size	3000
MAX time	3.75 s
MAX size	3000
Number of records	1

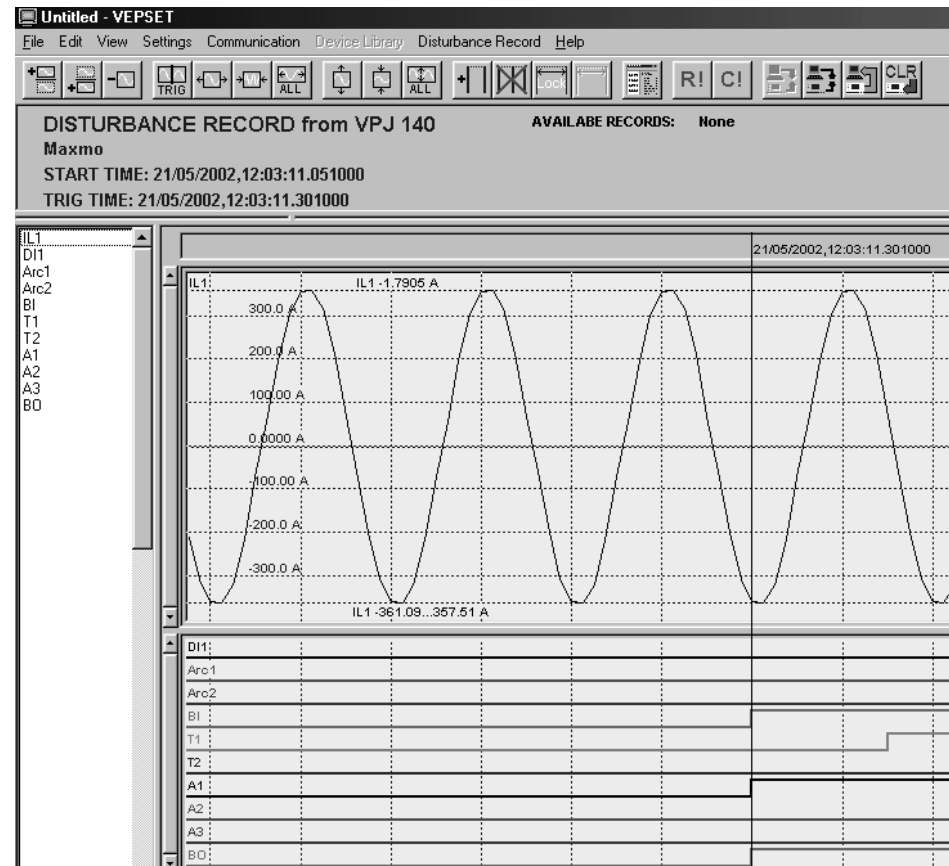
RECORDER LOG				
	Status	Trig date	time	ms
[1]	Run	-	-	0 ms

Manual trig	-
Clear oldest buffer	-
Clear all buffers	-
Status	Run
Time status	50 %
Readable records	0

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Disturbance recorder

The disturbance waveform recordings are evaluated by the VEPSET software.



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Primary measurements

Primary measurements

Phase currents IL1, IL2, IL3, IL

Residual current: I_0 (A), I_0 (%)

Phase unbalance: I_2 / I_1

15 min average on IL

IL maximum

Frequency: f

15 min average on IL1, IL2, IL3, IL and I_0 ⁽¹⁾

15 min maximum on IL1, IL2, IL3, IL and I_0 ⁽¹⁾

Current diagram ⁽¹⁾

1) Using VEPSET software

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Analog output

Analog output

One measured signal (IL1, IL2, IL3, IL, Io, I2/I1, f and I_Fault) can be linked in the output

Output signal range is
minimum: 0 ... 19 mA
maximum: 1 ... 20 mA

mA test mode in order to
calibrate the receiving
device

ANALOG OUTPUT	
Analog output	4.00 mA
A0 mA force flag	OFF
A0 coupling	IL
A0 minimum	0 A
A0 maximum	10000 A
Analog output min value	4 mA
Analog output max value	20 mA
A0 Coupling = fault current	
Fault current to A0	NotInUse
Fault Current stage connected	I>

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Example of the arc protection and fault current transfer to the network control system

Arc protection
made by feeder
protection relay

Arc sensors located
in the busbar
compartment

The fault current
measured from the
incomer is
transferred to the
control room as a
mA message

