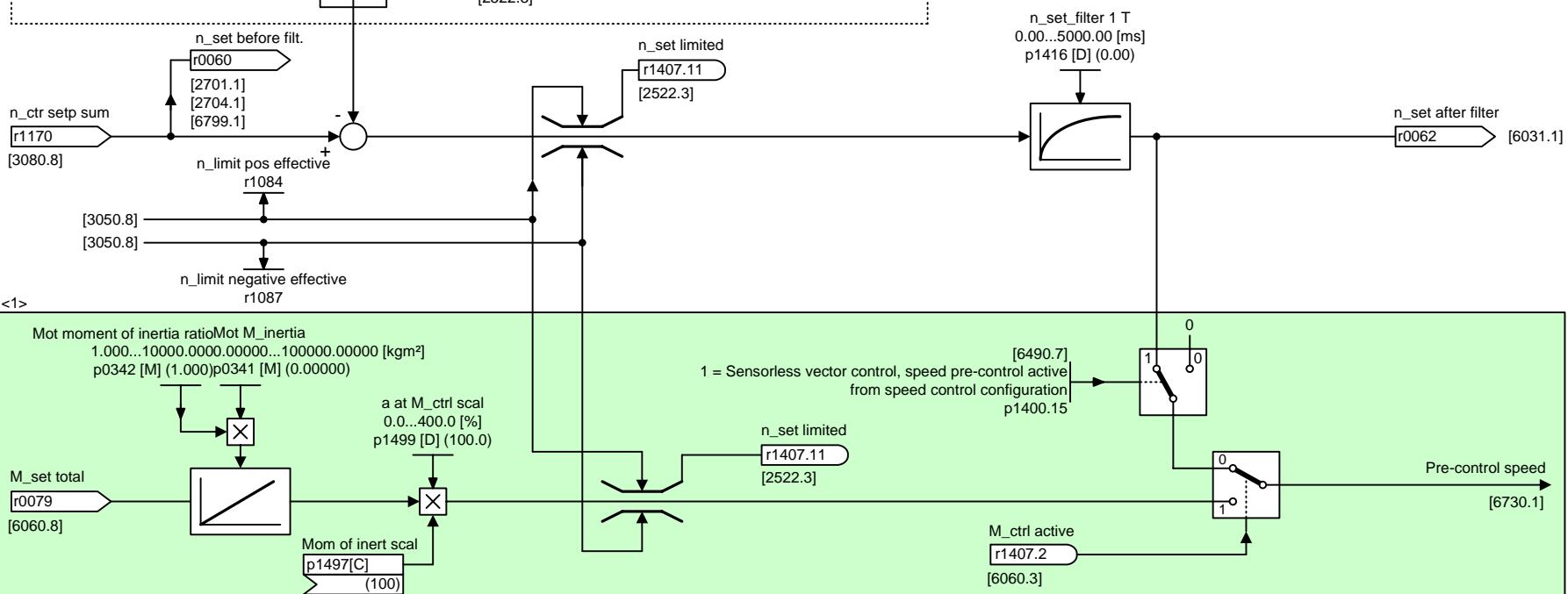
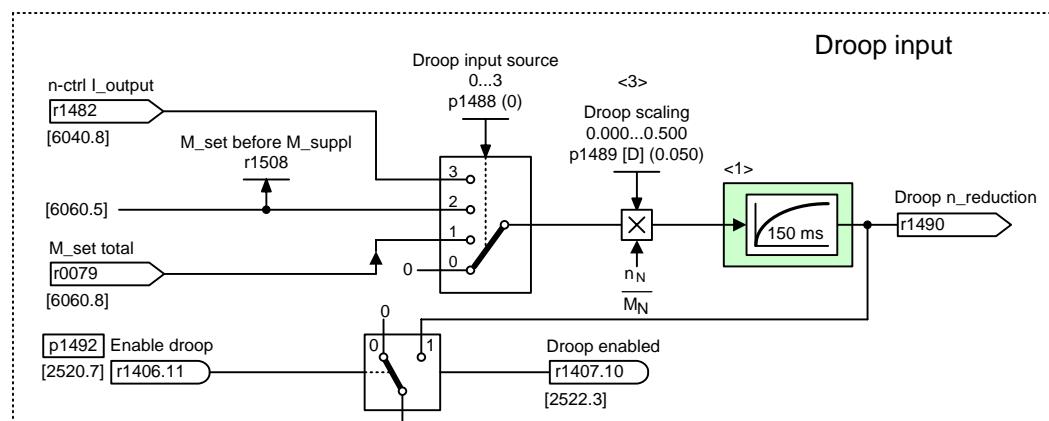


Droop input



<1> Only for vector control without encoder. <3> Scaling: p1489 = 0.100 - for a rated motor torque of r0333 - results in a speed setpoint reduction of 0.1 x p0311.

<2> Refer to speed actual value smoothing [6040.2]

1

2

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7

8

DO: VECTOR

fp_6030_01_eng.vsd

Function diagram

- 6030 -

Vector control - Speed setpoint, droop

18.04.07 V02.05.00

SINAMICS S